## Generalized Additive Models

David L Miller

#### Overview

- What is a GAM?
- What is smoothing?
- How do GAMs work?
- Fitting GAMs using dsm
- Model checking

## What is a GAM?

#### "gam"

- 1. Collective noun used to refer to a group of whales, or rarely also of porpoises; a pod.
- 2. (by extension) A social gathering of whalers (whaling ships).

(via Natalie Kelly, CSIRO. Seen in Moby Dick.)

#### Generalized Additive Models

- Generalized: many response distributions
- Additive: terms add together
- Models: well, it's a model...

#### What does a model look like?

- Count  $\boldsymbol{n}_j$  distributed according to some count distribution
- Model as sum of terms



#### Mathematically...

Taking the previous example...

$$\begin{split} n_{j} &= A_{j} \hat{p}_{j} \exp \Bigl[\beta_{0} + s(y_{j}) + s(Depth_{j}) \Bigr] + \varepsilon_{j} \\ \text{where } \varepsilon_{j} \sim N(0,\sigma^{2}), \quad n_{j} \sim \text{count distribution} \end{split}$$

#### Mathematically...

Taking the previous example...

$$n_{j} = \mathbf{A}_{j} \hat{\mathbf{p}}_{j} \exp\left[\beta_{0} + s(y_{j}) + s(\text{Depth}_{j})\right] + \epsilon_{j}$$

where  $\epsilon_j \sim N(0, \sigma^2)$ ,  $n_j \sim \text{count distribution}$ 

- area of segment offset
- probability of detection in segment
- link function
- model terms

#### Response

$$\mathbf{n}_{j} = A_{j}\hat{p}_{j} \exp\left[\beta_{0} + s(y_{j}) + s(\text{Depth}_{j})\right] + \epsilon_{j}$$

where  $\epsilon_j \sim N(0, \sigma^2)$ ,  $n_j \sim count distribution$ 

#### Count distributions



- Response is a count (not not always integer)
- Often, it's mostly zero (that's complicated)
- Want response distribution that deals with that
- Flexible mean-variance relationship

#### Tweedie distribution



- $Var(count) = \varphi(count)^q$
- Common distributions are sub-cases:
  - $q = 1 \Rightarrow$  Poisson
  - $q = 2 \Rightarrow$  Gamma
  - $q = 3 \Rightarrow Normal$
- We are interested in 1 < q < 2
- (here  $q = 1.2, 1.3, \dots, 1.9$ )

#### Negative binomial



- Var(count) =(count) +  $\varkappa$ (count)<sup>2</sup>
- Estimate  $\varkappa$
- Is quadratic relationship a "strong" assumption?
- Similar to Poisson: Var(count) = (count)

Smooth terms

$$n_j = A_j \hat{p}_j \exp\left[\beta_0 + s(y_j) + s(\text{Depth}_j)\right] + \epsilon_j$$

where  $\epsilon_j \sim N(0, \sigma^2)$ ,  $n_j \sim \text{count distribution}$ 

#### Okay, but what about these "s" things?



- Think s=smooth
- Want to model the covariates flexibly
- Covariates and response not necessarily linearly related!
- Want some wiggles

## What is smoothing?

#### Straight lines vs. interpolation



- Want a line that is "close" to all the data
- Don't want interpolation
   we know there is "error"
- Balance between interpolation and "fit"

#### Splines

- Functions made of other, simpler functions
- Basis functions  $b_k$ , estimate  $\beta_k$
- $s(x) = \sum_{k=1}^{K} \beta_k b_k(x)$
- Makes the math(s) much easier



#### Measuring wigglyness

- Visually:
  - Lots of wiggles == NOT SMOOTH
  - Straight line == VERY SMOOTH
- How do we do this mathematically?
  - Derivatives!
  - (Calculus was a useful class afterall)

#### Wigglyness by derivatives



### Making wigglyness matter

- Integration of derivative (squared) gives wigglyness
- Fit needs to be penalised
- Penalty matrix gives the wigglyness
- Estimate the  $\beta_k$  terms but penalise objective
  - "closeness to data" + penalty

#### Penalty matrix

- $\bullet \ \ \text{For each} \ b_k \ \text{calculate the penalty} \\$
- Penalty is a function of  $\boldsymbol{\beta}$ 
  - $\lambda \beta^{\mathrm{T}} S \beta$
- S calculated once
- smoothing parameter ( $\lambda$ ) dictates influence

#### Smoothing parameter



#### How wiggly are things?

- We can set **basis complexity** or "size" (k)
  - Maximum wigglyness
- Smooths have effective degrees of freedom (EDF)
- EDF < k
- $\bullet \; \mathsf{Set} \, k \, \text{``large enough''} \\$

## Okay, that was a lot of theory...

## Fitting GAMs using dsm

## Translating maths into R $n_j = A_j \hat{p}_j \exp[\beta_0 + s(y_j)] + \epsilon_j$

where  $\epsilon_j \sim N(0, \sigma^2)$ ,  $n_j \sim \text{count distribution}$ 

- inside the link: formula=count ~ s(y)
- response distribution: family=nb() or family=tw()
- detectability: ddf.obj=df\_hr
- offset, data: segment.data=segs, observation.data=obs

#### Your first DSM

## (method="REML" uses REML to select the smoothing parameter)

dsm is based on mgcv by Simon Wood

#### What did that do?

```
summary(dsm_x_tw)
```

```
Family: Tweedie(p=1.326)
Link function: log
Formula:
count ~ s(x) + offset(off.set)
Parametric coefficients:
             Estimate Std. Error t value Pr(>|t|)
(Intercept) -19.7008 0.2277 -86.52 <2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Approximate significance of smooth terms:
edf Ref.df F p-value
s(x) 4.962 6.047 6.403 1.07e-06 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
R-sq.(adj) = 0.0283 Deviance explained = 17.7%
-REML = 409.94 Scale est. = 6.0413 n = 949
```

#### Plotting



- plot(dsm\_x\_tw)
- Dashed lines indicate +/-2 standard errors
- Rug plot
- On the link scale
- EDF on y axis

#### Adding a term

• Just use +

#### Summary

```
summary(dsm_xy_tw)
```

```
Family: Tweedie(p=1.306)
Link function: log
Formula:
count ~ s(x) + s(y) + offset(off.set)
Parametric coefficients:
            Estimate Std. Error t value Pr(>|t|)
(Intercept) -19.9801 0.2381 -83.93 <2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Approximate significance of smooth terms:
       edf Ref.df F p-value
s(x) 4.943 6.057 3.224 0.004239 **
s(y) 5.293 6.419 4.034 0.000322 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
R-sq.(adj) = 0.0678 Deviance explained = 27.3%
-REML = 399.84 Scale est. = 5.3157 n = 949
```

#### Plotting

plot(dsm\_xy\_tw, scale=0, pages=1)



- scale=0: each plot on different scale
- pages=1: plot together

#### Bivariate terms

- Assumed an additive structure
- No interaction
- We can specify s(x,y) (and s(x,y,z,...))

#### Thin plate regression splines

- Default basis
- One basis function per data point
- Reduce # basis functions (eigendecomposition)
- Fitting on reduced problem
- Multidimensional

#### Thin plate splines (2-D)



#### Bivariate spatial term

#### Summary

```
summary(dsm_xyb_tw)
```

```
Family: Tweedie(p=1.29)
Link function: log
Formula:
count ~ s(x, y) + offset(off.set)
Parametric coefficients:
             Estimate Std. Error t value Pr(>|t|)
(Intercept) -20.1638 0.2477 -81.4 <2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Approximate significance of smooth terms:
edf Ref.df F p-value
s(x,y) 16.89 21.12 4.333 3.73e-10 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
R-sq.(adj) = 0.102 Deviance explained = 34.5%
-REML = 394.86 Scale est. = 4.8248 n = 949
```

#### Plotting... erm...



#### Let's try something different

#### vis.gam(dsm\_xyb\_tw, view=c("x","y"), plot.type="contour", too.far=0.1, asp=1)



- Still on link scale
- too.far excludes points far from data

#### Comparing bivariate and additive models



## Model checking

"perhaps the most important part of applied statistical modelling"

Simon Wood

### Model checking

- As with detection function, checking is important
- Want to know the model conforms to assumptions
- What assumptions should we check?

#### What to check

- Convergence (not usually an issue)
- Basis size is big enough
- Residuals

## Basis size

#### Basis size (k)

- Set k per term
- e.g. s(x, k=10) or s(x, y, k=100)
- Penalty removes "extra" wigglyness
  - up to a point!
- (But computation is slower with bigger k)

#### Checking basis size

gam.check(dsm\_x\_tw)

Method: REML Optimizer: outer newton full convergence after 7 iterations. Gradient range [-3.08755e-06,4.928062e-07] (score 409.936 & scale 6.041307). Hessian positive definite, eigenvalue range [0.7645492,302.127]. Model rank = 10 / 10 Basis dimension (k) checking results. Low p-value (k-index<1) may indicate that k is too low, especially if edf is close to k'. k' edf k-index p-value s(x) 9.000 4.962 0.763 0.44

#### Increasing basis size

```
Method: REML Optimizer: outer newton
full convergence after 7 iterations.
Gradient range [-2.301246e-08,3.930757e-09]
(score 409.9245 & scale 6.033913).
Hessian positive definite, eigenvalue range [0.7678456,302.0336].
Model rank = 20 / 20
Basis dimension (k) checking results. Low p-value (k-index<1) may
indicate that k is too low, especially if edf is close to k'.
k' edf k-index p-value
s(x) 19.000 5.246 0.763 0.36
```

#### Sometimes basis size isn't the issue...

- Generally, double k and see what happens
- Didn't increase the EDF much here
- Other things can cause low "p-value" and "k-index"
- Increasing k can cause problems (nullspace)

# Don't throw away your residuals!

#### What are residuals?

- Generally residuals = observed value fitted value
- BUT hard to see patterns in these "raw" residuals
- Need to standardise deviance residuals
- Residual sum of squares  $\Rightarrow$  linear model
  - deviance  $\Rightarrow$  GAM
- Expect these residuals ~ N(0, 1)

#### Residual checking



Resids vs. linear pred.



Histogram of residuals

**Response vs. Fitted Values** 





#### Shortcomings

- gam.check left side can be helpful
- Right side is victim of artifacts
- Need an alternative
- "Randomised quanitle residuals" (experimental)
  - rqgam.check
  - Exactly normal residuals (left side useless)

#### Randomised quantile residuals



Histogram of residuals





Response vs. Fitted Values







#### Residuals vs. covariates



х

#### Residuals vs. covariates (boxplots)



х

#### Example of "bad" plots



#### Example of "bad" plots



#### Residual checks

- Looking for patterns (not artifacts)
- This can be tricky
- Need to use a mixture of techniques

## Let's have a go...