

# Measures of Precision

# Overview

- How to quantify uncertainty
- Why variance is important
- Components of variation in distance sampling
- Controlling variance
- Estimating variance
  - Analytic
  - Bootstrap
- Confidence Intervals

# How do estimates behave?

Consider an artificial population

$D = 500$  per unit<sup>2</sup> (no density gradient)

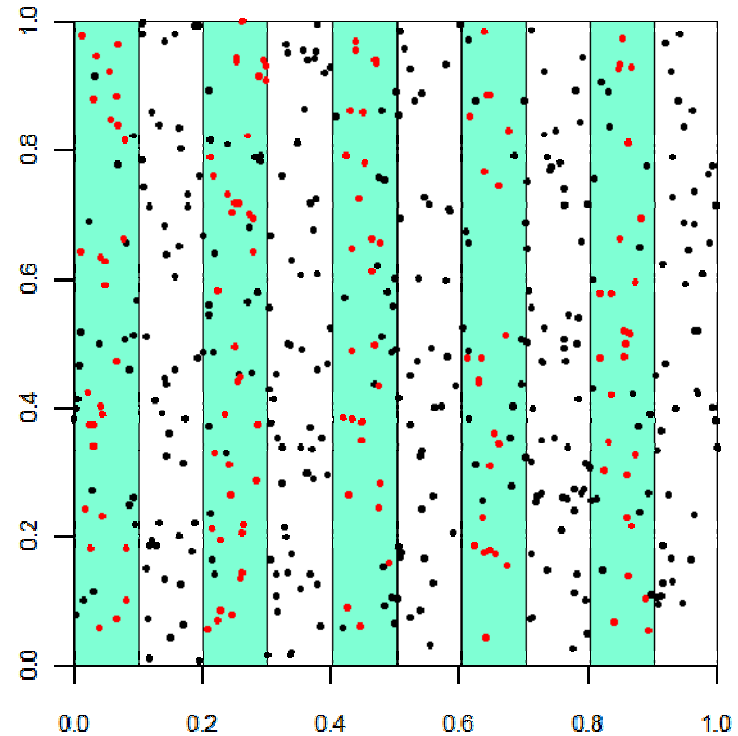
Design: 5 transects equally-spaced  
( $w=0.05$ )

Results:

$$n = 140$$

$$\hat{f}(0) = 34.6$$

$$\hat{D} = 484.4$$



# How do estimates behave?

Consider a duplicate survey

Same population model

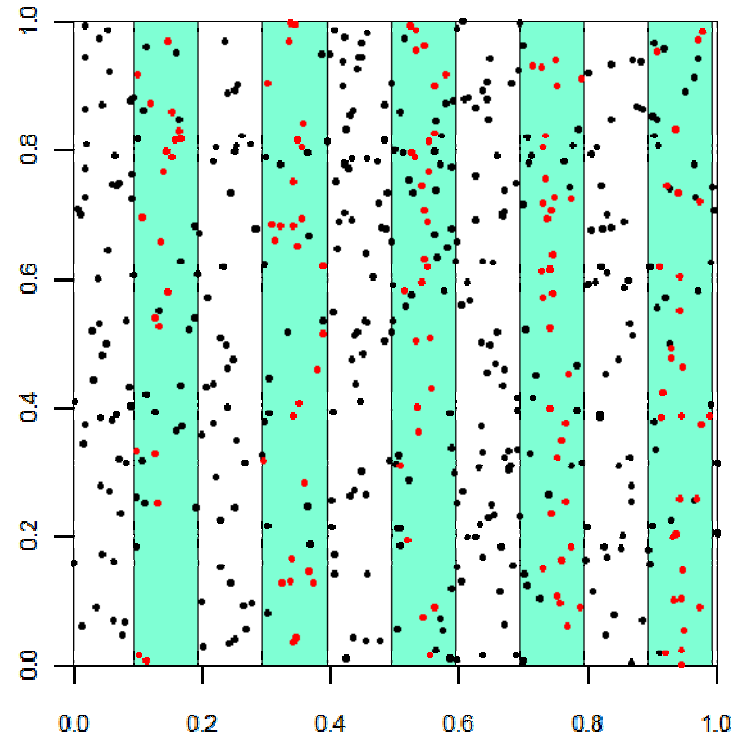
Same survey design (with a new random start point)

Results:

$$n = 139$$

$$\hat{f}(0) = 37.6$$

$$\hat{D} = 522.1$$



# How do estimates behave?

Imagine repeating this process over and over, using the same survey design and a population drawn from the same density model

Each survey will yield:

A different value for  $n$

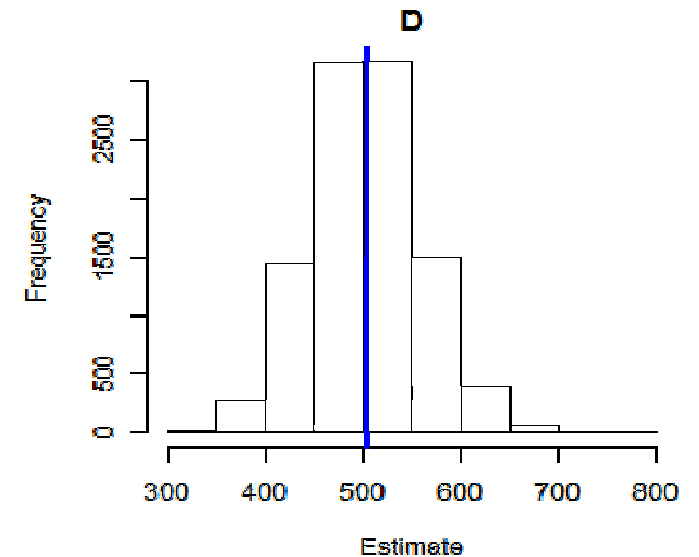
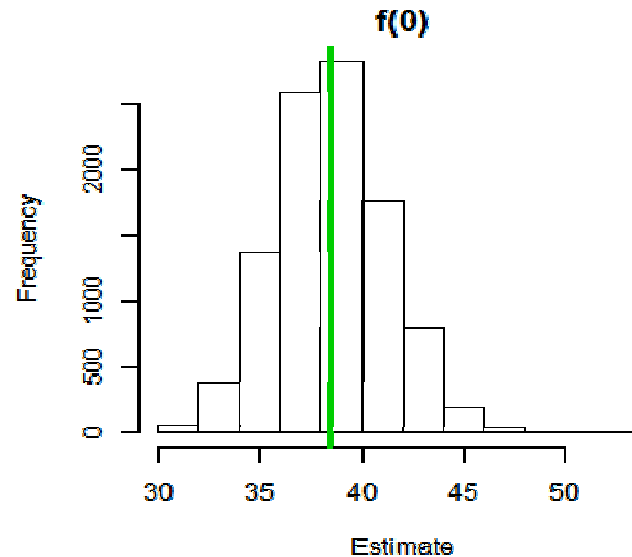
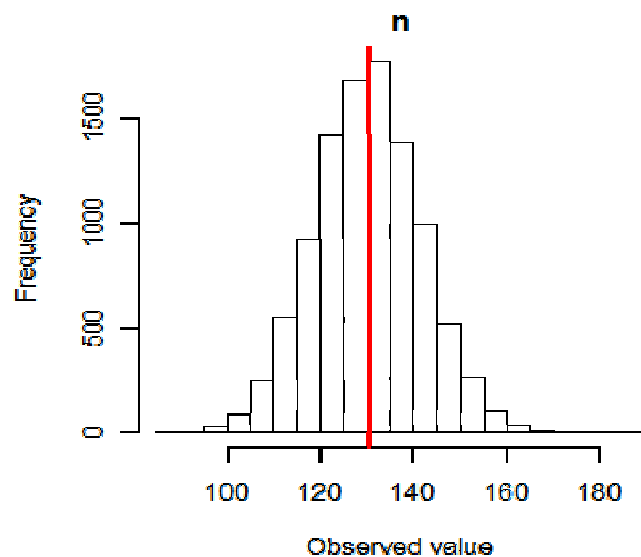
A different value for  $\hat{f}(0)$

A different value for  $\hat{D}$

# How do estimates behave?

What happens if we repeat this simulated survey 10,000 times?

We end up with **distributions** for  $n$ ,  $\hat{f}(0)$  and  $\hat{D}$



Note,  $\hat{f}(0) = 1/w\hat{P}_a$

# How do estimates behave?

We are interested in the **hypothetical long-run** behaviour of our estimator

$$\hat{D} = \frac{n}{2wL\hat{P}_a}$$

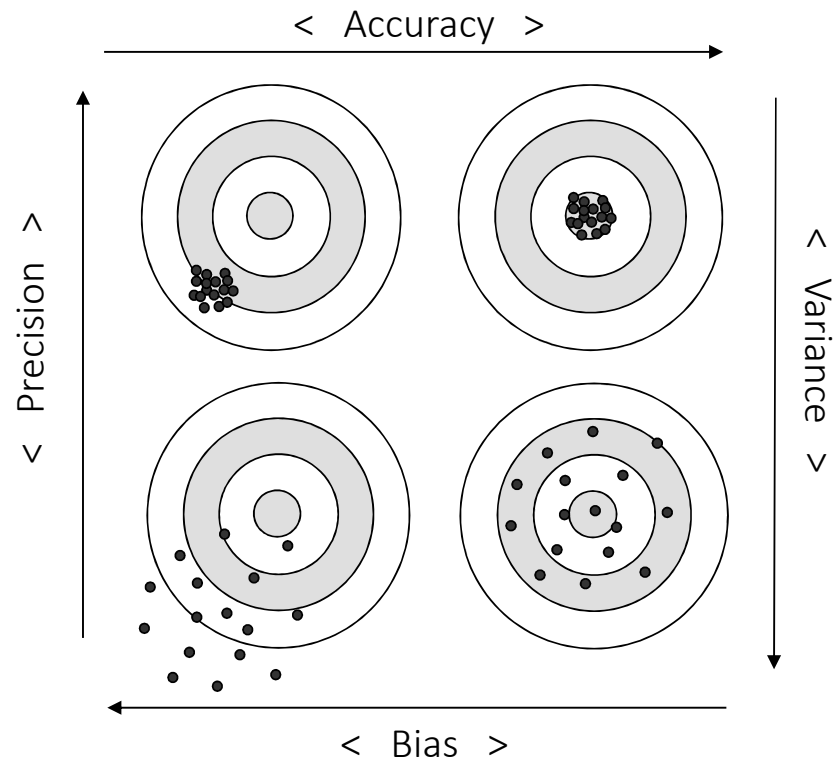
How variable are the estimates?

E.g. what is the variance of the distribution for  $\hat{D}$ ?

What is the average value of the estimates?

E.g. is the distribution for  $\hat{D}$  centred on the truth?

# Bias vs. Variance



Low precision = high variance = high uncertainty



# Quantifying uncertainty

Different ways of measuring uncertainty:

1. **Variance** = the average squared difference from the mean (the inverse of precision)

If the estimator for  $D$  is unbiased, then

$$\text{Var}[\hat{D}] = E[(\hat{D} - D)^2]$$

2. **Standard error** = the standard deviation of an estimator (i.e. the square root of estimator variance)

$$\text{Se}[\hat{D}] = \sqrt{\text{Var}[\hat{D}]}$$

# Quantifying uncertainty

3. **Coefficient of Variation (CV)** = the standard error divided by the mean (i.e. a standardised version of the standard error)

$$CV[\hat{D}] = \frac{Se[\hat{D}]}{E[\hat{D}]}$$

Useful for comparing variances when the scale and/or the units of measurement differ

E.g. consider two variables: X has mean = 100 and variance = 400,  
Y has mean = 1 and variance = 0.04

$$CV[X] = \frac{\sqrt{400}}{100} = \frac{20}{100} = 0.2 = 20\% \quad CV[Y] = \frac{\sqrt{0.04}}{1} = \frac{0.2}{1} = 0.2 = 20\%$$

# Quantifying uncertainty

4. **Confidence Interval (CI)** = a range of plausible values for the truth

Calculations are based on variance

Different ways to calculate CIs, depending on the data, e.g.

*Normal*

*Lognormal (available in Distance)*

*Bootstrap (available in Distance)*

More about CIs later...

# Why is variance important?

- In a real survey, we use an estimator and the survey data to produce a single estimate for  $D$
- If the estimator variance is low, then individual estimates are more likely to be close to the truth (assuming low bias)
- If estimator variance is high, then individual estimates are more likely to be far from the truth
- **For reliable results, we want estimators with LOW variance (and low bias!)**

# Variance by components

We can break down the familiar distance sampling density estimator (for line transects with no clusters) into three components:

$$\hat{D} = \frac{n}{2wL\hat{P}_a} = \frac{1}{2w} \times \frac{n}{L} \times \frac{1}{\hat{P}_a}$$

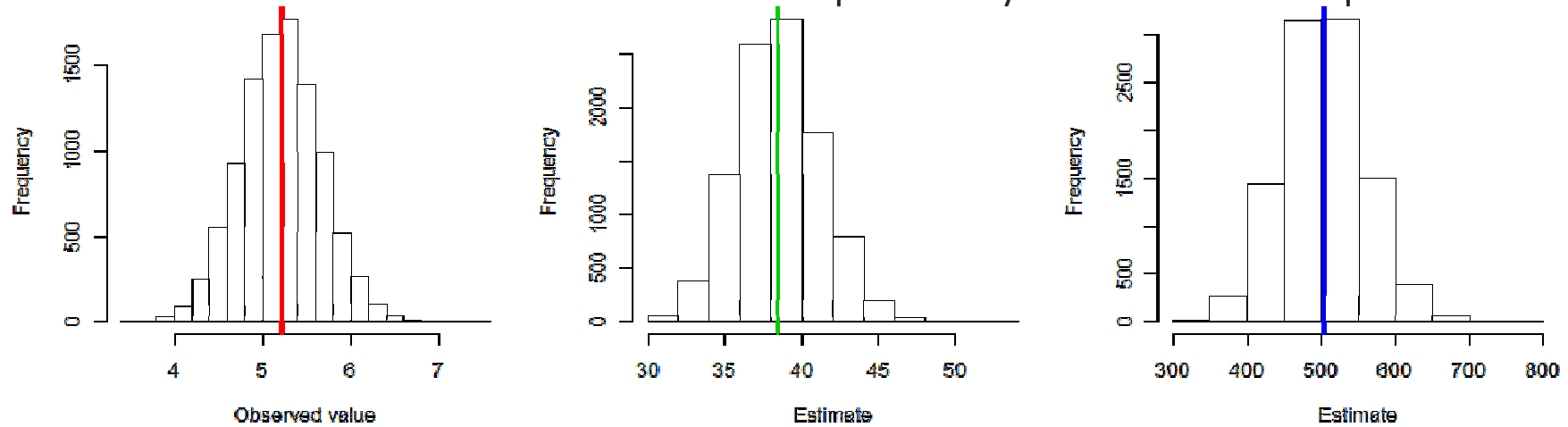
Constant  
(no variance)

Encounter rate

Detection function

# Variance by components

We can calculate variance measures separately for each component



	$n/L$	$\hat{f}(0)$	$\hat{D}$
Mean	26.1	38.5	500.6
Se	2.27	2.71	56.34
CV	8.69 %	7.04 %	11.26 %

## Variance by components

- The variance of  $\hat{D}$  is affected by the variance of its components
- If the variance of  $n$  is high, then the variance of  $\frac{n}{L}$  will be high and the variance of  $\hat{D}$  will be high
- Similarly, if the variance of  $\hat{P}_a$  is high then the variance of  $\hat{D}$  will be high
- So for reliable estimates, we want  $Var\left[\frac{n}{L}\right]$  and  $Var[\hat{P}_a]$  to be low

# Variance by components

Distance provides several variance measures for each component

	Estimate	SE	CV					
Average p	0.3491863	0.02160949	0.06188528					
N in covered region	300.6991117	30.11200030	0.10013997					
<b>Summary statistics:</b>								
Region	Area Covered	Area Effort	n	k	ER	se.ER	cv.ER	
1 Default	1	3436.8	48	105	12	2.1875	0.3169604	0.1448962
<b>Abundance:</b>								
Label	Estimate	se	cv	lcl	ucl	df		
1 Total	8.749392	1.378541	0.1575585	6.270328	12.20859	15.32522		
<b>Density:</b>								
Label	Estimate	se	cv	lcl	ucl	df		
1 Total	0.08749392	0.01378541	0.1575585	0.06270328	0.1220859	15.32522		



# Encounter rate variance

The **encounter rate** =  $n/L$  = the number of detections per unit of distance

The variance of  $n/L$  is related to the variance of  $n$ , and therefore to the variances of counts for individual transects

Therefore, if counts from individual transects are highly variable the variance of  $n/L$  will also be high  $Var[n] = Var[n_1] + \dots + Var[n_k]$  ← **assumes independence**

# Controlling variance

- We can use this knowledge of encounter rate variance to help design good surveys
- Three main ways we can reduce encounter rate variance:
  - Use systematic survey designs
  - Run transects parallel to density gradients
  - Use designs with several transects

## Estimating variance – Analytic

We can describe the relationship between the variance of  $\hat{D}$  and the variance of its components more formally using a useful approximation known as the **Delta method**

$$\{cv(\hat{D})\}^2 = \left\{cv\left(\frac{n}{L}\right)\right\}^2 + \{cv(\hat{P}_a)\}^2$$

Rule: when two or more components are multiplied together, **squared CVs add**

## Estimating variance – Analytic

	$\frac{n}{L}$	$\hat{f}(0)$	$\hat{D}$
Mean	26.1	38.5	500.6
Se	2.27	2.71	56.34
CV	8.69 %	7.04 %	11.26 %

We can check this approximation works using the results of our simulation,

$$\{cv(\hat{D})\}^2 = 0.1125^2 = 0.01266$$

$$\left\{cv\left(\frac{n}{L}\right)\right\}^2 + \{cv(\hat{P}_a)\}^2 = 0.0869^2 + 0.0704^2 = 0.01251$$

We can rearrange the squared CV to get an estimate of the variance

$$var(\hat{D}) \approx \hat{D}^2 \times \{cv(\hat{D})\}^2$$

## Estimating variance – Analytic

- To estimate  $var(n/L)$  we need to use data from the individual lines (or points)
- **A minimum of 20 replicate lines (or points)** is recommended for obtaining a reliable estimate of encounter rate variance
- The (improved) formula used in Distance:

$$\left\{cv\left(\frac{n}{L}\right)\right\}^2 = \frac{k}{n^2(k-1)} \sum_{i=1}^k l_i^2 \left(\frac{n_i}{l_i} - \frac{n}{L}\right)^2$$

$k$  = number  
of lines

$l_i$  = effort  
for line  $i$

$n_i$  = count  
for line  $i$

# Estimating variance – Analytic

Estimate	SE	CV						
Average p	0.3491863	0.02160949	0.06188528					
N in covered region	300.6991117	30.11200030	0.10013997					
Summary statistics:								
Region	Area Covered	Area	Effort	n	k	ER	se.ER	cv.ER
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Abundance:								
Label	Estimate	se	cv	lcl	ucl	df		
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Density:								
Label	Estimate	se	cv	lcl	ucl	df		
1 Total	0.08749392	0.01378541	0.1575585	0.06270328	0.1220859	15.32522		

Component percentages of variance:		
.Label	Detection	ER
Total	15.43	84.57

**Abundance and Density always have the same CV**

## Estimating variance – Analytic

To find the **relative contributions** of each component we take the ratio of squared CVs

E.g.  $100\% \times \frac{\{cv(\hat{P}_a)\}^2}{\{cv(\hat{D})\}^2} =$  The percentage relative contribution made by  $\hat{P}_a$

Component	Typical values	
	Line	Point
Encounter rate	70-80%	40-50%
Detection function	<30%	>50%

# Estimating variance – Analytic

	Estimate	SE	CV
Average p	0.3491863	0.02160949	0.06188528
N in covered region	300.6991117	30.11200030	0.10013997

Summary statistics:

Region	Area Covered	Area	Effort	n	k	ER	se.ER	cv.ER
1 Default	1	3436.8	48	105	12	2.1875	0.3169604	0.1448962

Abundance:

Label	Estimate	se	cv	lcl	ucl	df
1 Total	8.749392	1.378541	0.1575585	6.270328	12.20859	15.32522

Density:

Label	Estimate	se	cv	lcl	ucl	df
1 Total	0.08749392	0.01378541	0.1575585	0.06270328	0.1220859	15.32522

Component percentages of variance:

.Label	Detection	ER
Total	15.43	84.57

$$= \frac{0.0619^2}{0.1576^2} \times 100$$

$$= \frac{0.1449^2}{0.1576^2} \times 100$$



# Estimating variance – Bootstrap

- Works well if the original sample is **large and representative**
- The distribution of density estimates approximates the true distribution that we would (theoretically) get from duplicate surveys
- The variance of the bootstrap estimates can be used as an estimate of the true variance
- In Distance we **resample the individual transects**

# Estimating variance – Bootstrap

- For example, consider a survey with 12 replicate lines
  - Bootstrap sample 1:
    - *Transects:* 5, 12, 1, 7, 6, 11, 7, 6, 9, 7, 11, 2
    - *Density estimate* =  $D_1$
  - Bootstrap sample 2:
    - *Transects:* 3, 4, 9, 1, 12, 7, 8, 11, 1, 3, 2, 12
    - *Density estimate* =  $D_2$
- Do this B times and use the variance of the B density estimates as an estimate of  $var(\hat{D})$

# Estimating variance – Bootstrap

Basic R command to generate a bootstrap:

```
bootdht(model, flatfile, nboot, summary_fun)
```

`model` – detection function model

`flatfile` – data object used to fit model

`summary_fun` – function to harvest required statistic from each bootstrap sample

`nboot` – the number of bootstrap samples to use

By default, transects  
are sampled

test on a small number first  
to ensure all is properly set  
up

# Confidence Intervals

- Confidence intervals (CIs) give us a **range of plausible values** for the truth
- Constructed using data from a single sample
- If we were to carry out multiple surveys and construct 95% CIs from each survey, we would expect 95% of those CIs to contain the true value
- To calculate CIs we need to know the **shape** of the distribution of estimates

# Confidence Intervals - Analytic

- Two choices:

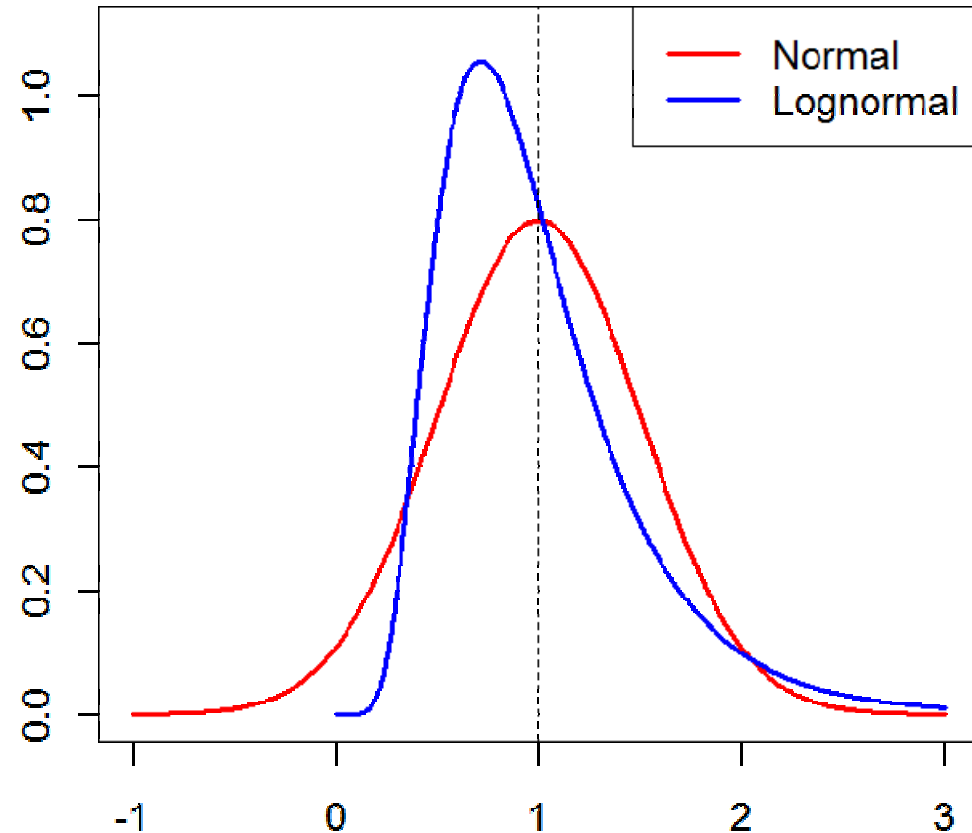
- **Normal**

- *symmetrical*
- *easy to use*
- *allows negative values*

- **Lognormal**

- *asymmetric (skewed)*
- *trickier to use*
- *typically higher interval limits*
- *does not allow negative values*

mean = 1, se = 0.5



Estimate

# Confidence Intervals - Analytic

Distance uses 95% lognormal CIs

Abundance:

	Label	Estimate	se	cv	lcl	ucl	df
1	Total	8.749392	1.378541	0.1575585	6.270328	12.20859	15.32522

Density:

	Label	Estimate	se	cv	lcl	ucl	df
1	Total	0.08749392	0.01378541	0.1575585	0.06270328	0.1220859	15.32522

$$\left(\frac{\hat{D}}{C}, \hat{D} \times C\right) \quad C = \exp \left[ 1.96 \sqrt{\ln \left\{ 1 + (cv(\hat{D}))^2 \right\}} \right]$$

# Confidence Intervals – Bootstrap

We can use the bootstrap estimates to construct CIs for the true density in two ways:

## Parametric

Use the lognormal CI method with the bootstrap estimate of variance instead of the analytic estimate

## Non-parametric

Place the bootstrap estimates in order of increasing size and use percentiles as the CI limits (e.g. for a 95% CI using 999 bootstrap estimates, take the 25th estimate as the lower limit and the 975<sup>th</sup> estimate as the upper limit)

# Confidence Intervals – Bootstrap

The nonparametric option is provided in Distance

Bootstrap results

```
Boostraps          : 999
Successes          : 999
Failures           : 0
```

```
      Estimate      se      ucl      lcl      cv
N         8.58    1.44    11.67    5.94    0.17
D         0.09    0.01     0.12    0.06    0.17
```

Standard error divided  
by the mean

Option 2 (non-parametric)



# Further reading

## Further reading

- Section 3.6 of Buckland et al. (2001) Introduction to Distance Sampling
- Fewster et al. (2009) Estimating the encounter rate variance in distance sampling. Biometrics 65: 225-236.
- Sections 6.3.1.2 and 6.3.2.2 of Buckland et al. (2015) Distance Sampling: Methods and Applications.

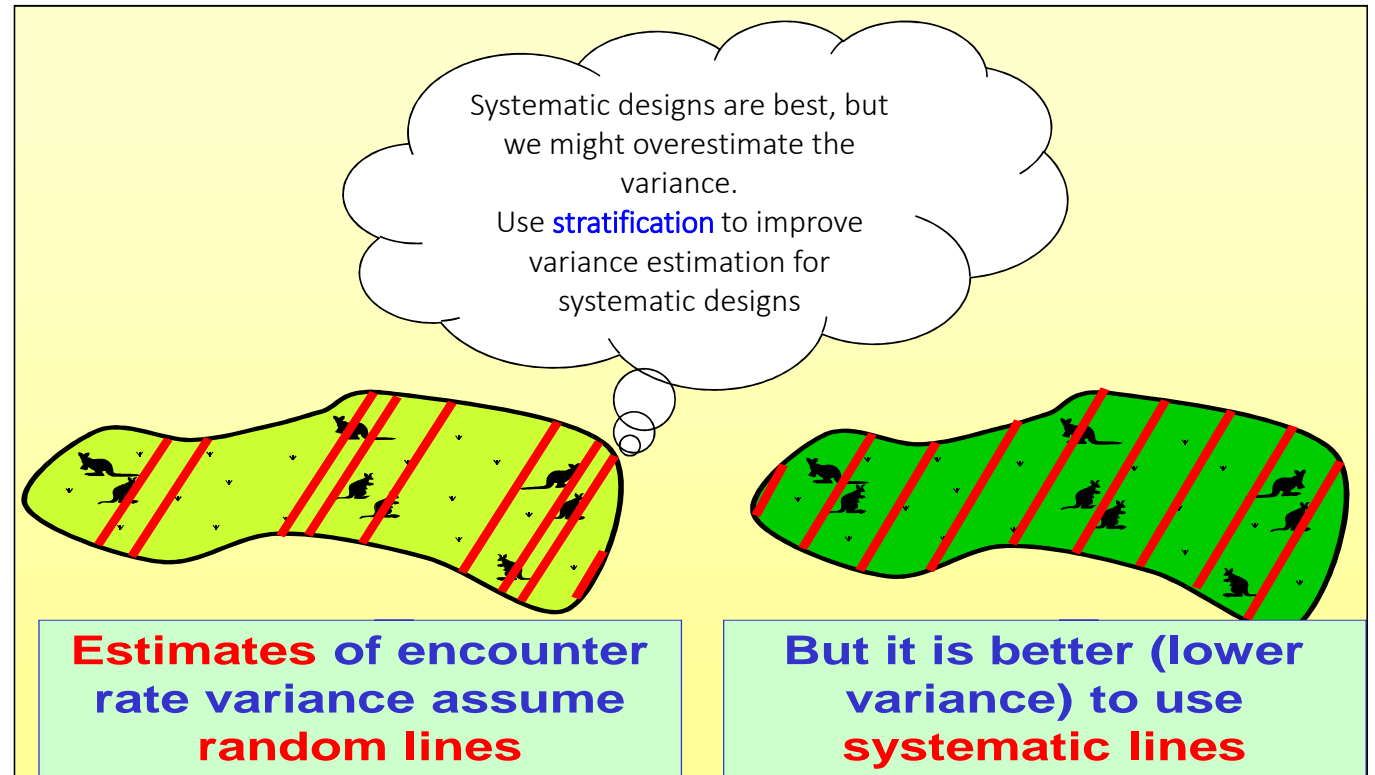
# Producing a better estimate of variance when systematic samplers are used

- Fewster, RM, Buckland, ST, Burnham, KP, Borchers, DL, Jupp, PE, Laake, JL, and Thomas, L. 2009. Estimating the encounter rate in distance sampling. *Biometrics* 65: 225-236.

# Systematic samples

## Problem:

Systematic designs give the best variance, but the worst variance estimation!

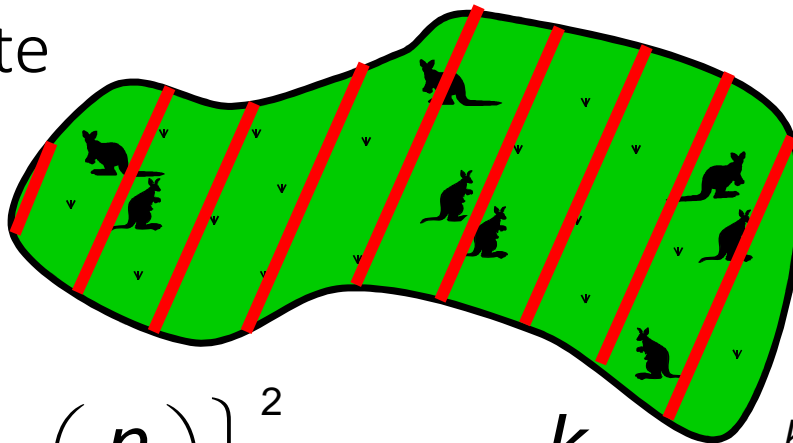


No unbiased estimator exists for estimating variance from a single systematic sample

# Systematic samples advice

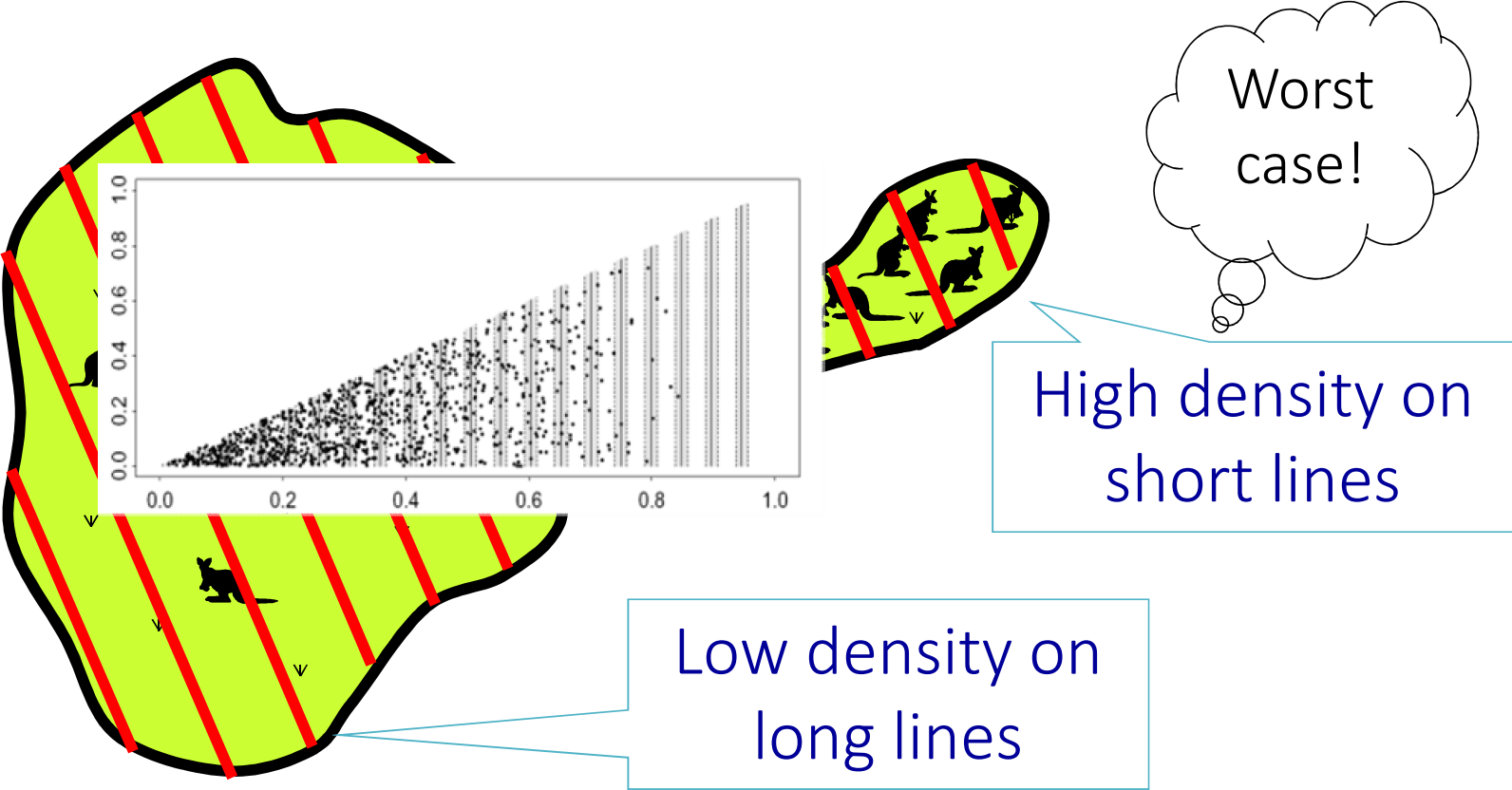
Usually, do nothing!

Variance estimation based on random lines will not be perfect, but adequate

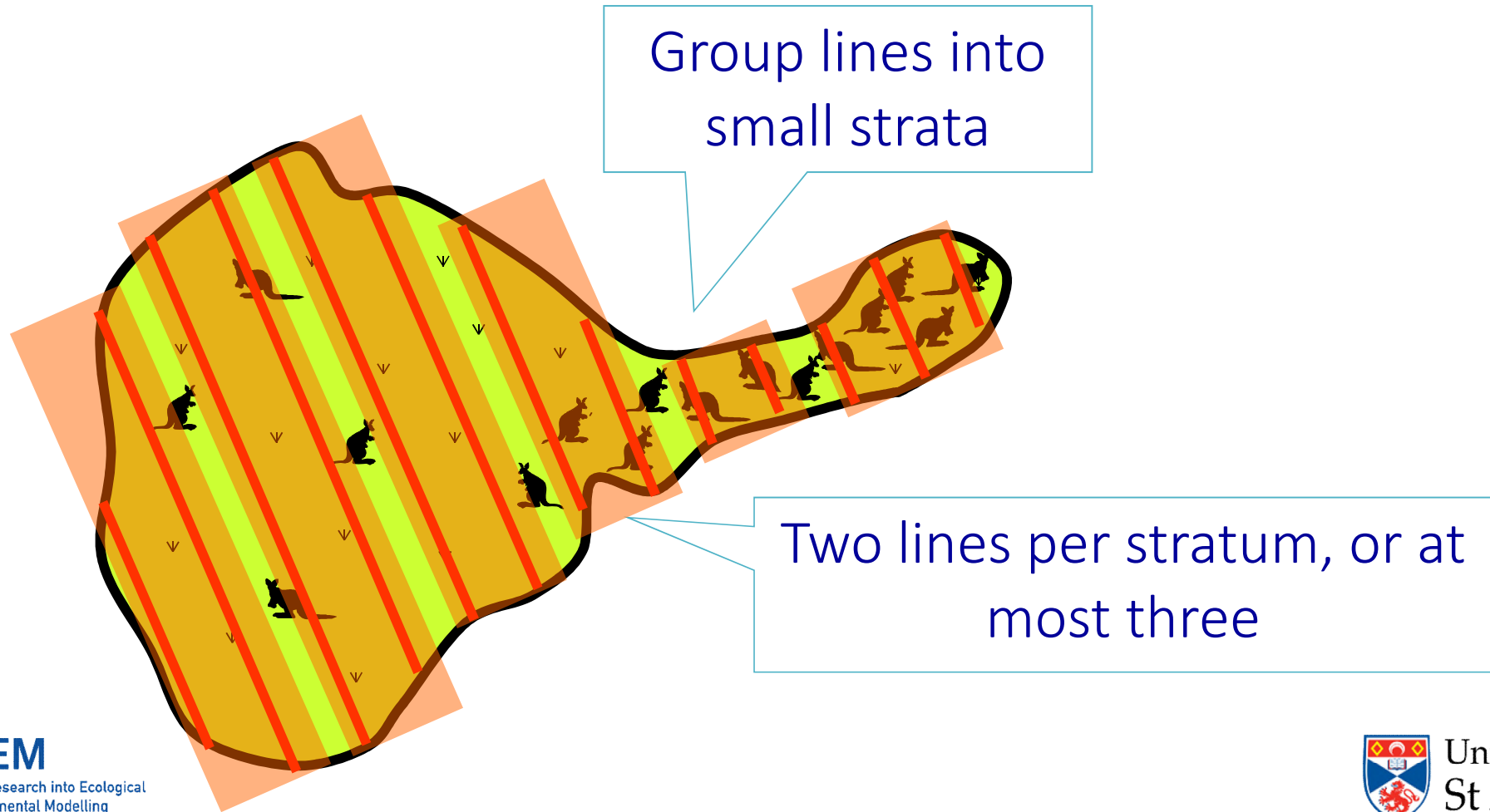


$$\left\{ \text{cv} \left( \frac{n}{L} \right) \right\}^2 = \frac{k}{n^2 (k - 1)} \sum_{i=1}^k l_i^2 \left( \frac{n_i}{l_i} - \frac{n}{L} \right)^2$$

If there are strong trends, variance might be significantly overestimated



# Post-stratification can give much better variance estimates



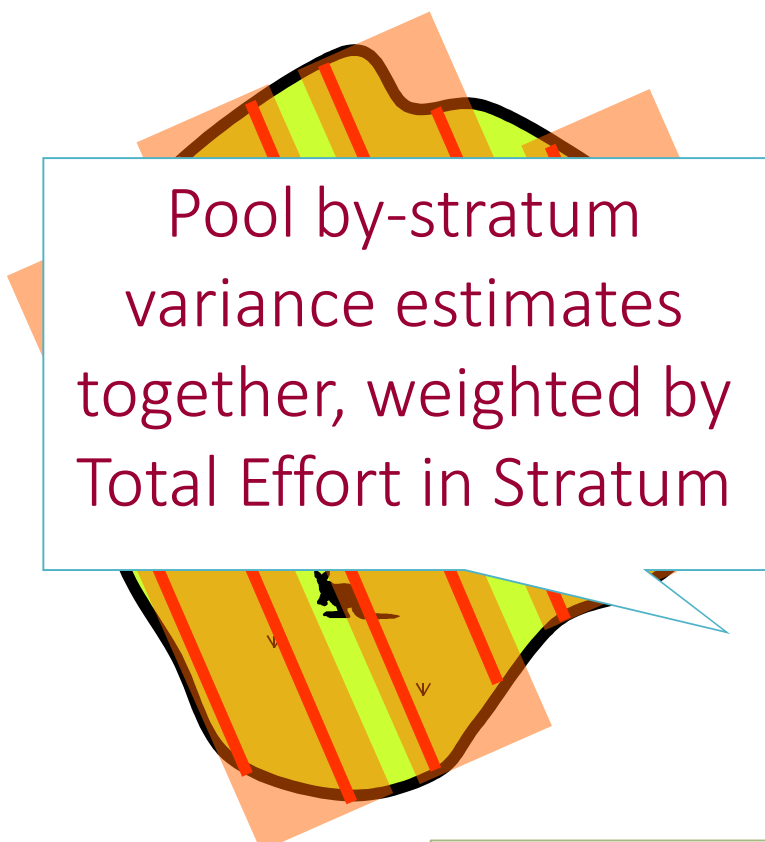
## In Distance:

The encounter rate variance can be specified in the `dht2` function with the `er_est` argument

```
dht2(model, flatfile, er_est)
```

- The options follow the notation used in Fewster *et al.* (2009)
- The default is `er_est="R2"` – random line placement with unequal line length
- For systematic estimators, successive pairs of lines will be grouped together, according to the `Sample.Label` and so labels should be numeric (e.g. lines 1 and 2 grouped)
- If there are an odd number of lines, the last 3 will be grouped

## Post-stratification can give much better estimates of variance



Pool by-stratum  
variance estimates  
together, weighted by  
Total Effort in Stratum

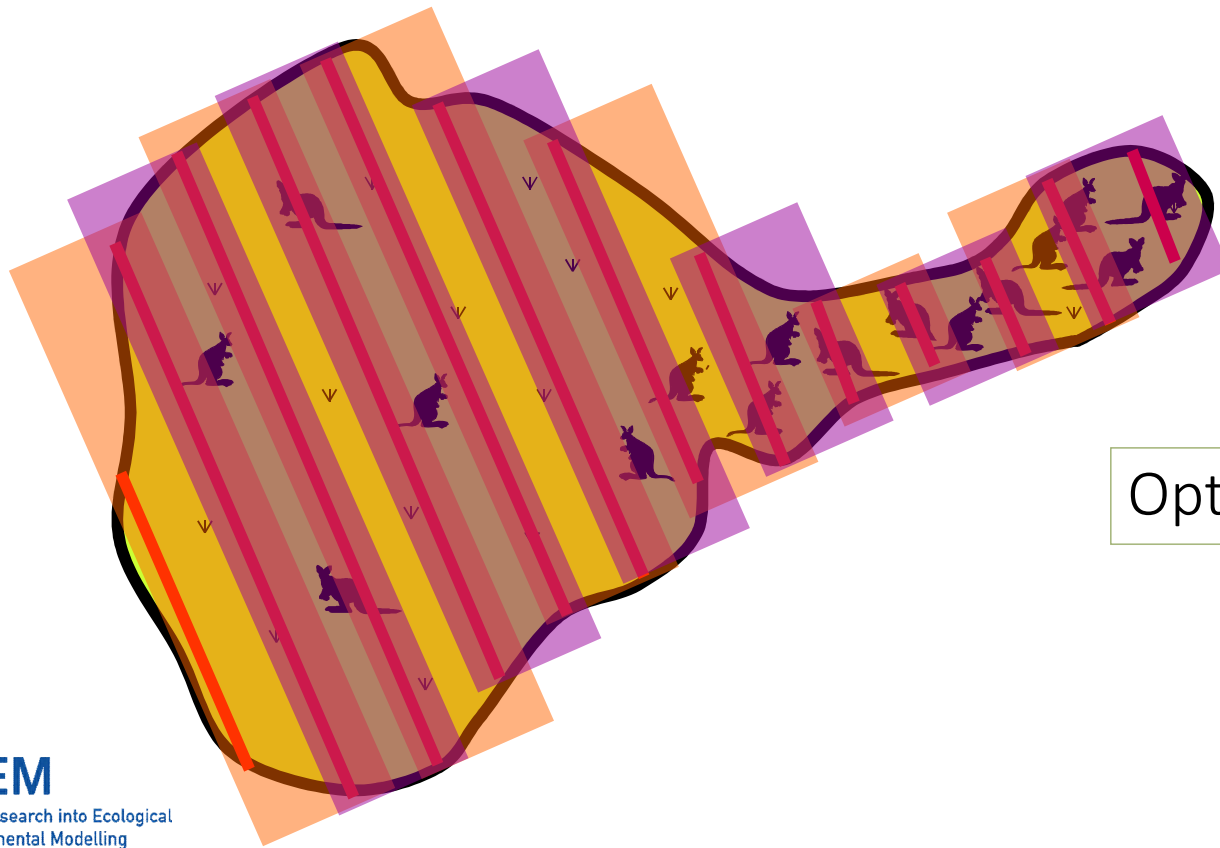
Trends **within** strata are minor;  
Estimate encounter rate variance  
separately for each stratum

$$\hat{\text{var}}\left(\frac{n}{L}\right) = \frac{1}{L^2} \sum_{h=1}^H L_h^2 \hat{\text{var}}_h\left(\frac{n_h}{L_h}\right)$$

Option is `er_est = "S2"`



Overlapping strata are even better, as you get a larger sample size of post-strata



Option is `er_est = "02"`

# Point transect surveys

Default (and only) option is `er_est="P2"`

